

# Justification of the short-pulse equation

Dmitry Pelinovsky (McMaster) and Guido Schneider (Stuttgart)

Department of Mathematics, McMaster University, Hamilton, Ontario, Canada  
<http://dmpeli.math.mcmaster.ca>

University of Loughborough, June 20, 2012

## References:

- Yu. Liu, D.P., A. Sakovich, Dynamics of PDE 6, 291-310 (2009)
- D.P., A. Sakovich, Communications in PDE 35, 613-629 (2010)
- D.P., G. Schneider, arXiv: 1108.5970

The **short-pulse equation** is a model for propagation of ultra-short pulses with few cycles on the pulse scale [Schäfer, Wayne 2004]:

$$u_{xt} = u + \frac{1}{6} (u^3)_{xx},$$

where all coefficients are normalized.

The short-pulse equation

- replaces the nonlinear Schrödinger equation for short wave packets
- features exact solutions for modulated pulses
- enjoys inverse scattering and an infinite set of conserved quantities

- T. Schafer and C.E. Wayne (2004) proved local existence in  $H^2(\mathbb{R})$ .
- A. Stefanov *et al.* (2010) considered a family of the generalized short-pulse equations

$$u_{xt} = u + (u^p)_{xx}$$

and proved scattering to zero for *small* initial data if  $p \geq 4$ .

- D.P. and A. Sakovich (2010) proved global well-posedness for *small* initial data if  $p = 3$ .
- Y. Liu, D.P. and A. Sakovich (2010) proved wave breaking for *large* initial data if  $p = 2$  and  $p = 3$ .
- **Remark:** Global existence for *small* initial data is still opened for  $p = 2$ .

# Integrability of the short-pulse equation

Let  $x = x(y, t)$  satisfy

$$\begin{cases} x_y = \cos w, \\ x_t = -\frac{1}{2}w_t^2. \end{cases}$$

Then,  $w = w(y, t)$  satisfies the sine–Gordon equation in characteristic coordinates [A. Sakovich, S. Sakovich, (2005), (2006)]:

$$w_{yt} = \sin(w).$$

## Lemma

Let the mapping  $[0, T] \ni t \mapsto w(\cdot, t) \in H_c^s$  be  $C^1$  and

$$H_c^s = \left\{ w \in H^s(\mathbb{R}) : \|w\|_{L^\infty} \leq w_c < \frac{\pi}{2} \right\}, \quad s \geq 1.$$

Then,  $x(y, t)$  is invertible in  $y$  for any  $t \in [0, T]$  and  $u(x, t) = w_t(y(x, t), t)$  solves the short-pulse equation

$$u_{xt} = u + \frac{1}{6} (u^3)_{xx}, \quad x \in \mathbb{R}, \quad t \in [0, T].$$

## Solutions of the short-pulse equation

A kink of the sine–Gordon equation gives a *loop solution* of the short-pulse equation:

$$\begin{cases} u = 2 \operatorname{sech}(y + t), \\ x = y - 2 \tanh(y + t). \end{cases}$$

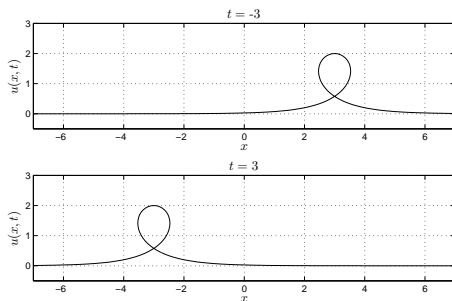


Figure: The loop solution  $u(x, t)$  to the short-pulse equation

# Solutions of the short-pulse equation

A breather of the sine–Gordon equation gives a *modulated pulse solution*:

$$\begin{cases} u(y, t) = 4mn \frac{m \sin \psi \sinh \phi + n \cos \psi \cosh \phi}{m^2 \sin^2 \psi + n^2 \cosh^2 \phi} = u\left(y - \frac{\pi}{m}, t + \frac{\pi}{m}\right), \\ x(y, t) = y + 2mn \frac{m \sin 2\psi - n \sinh 2\phi}{m^2 \sin^2 \psi + n^2 \cosh^2 \phi} = x\left(y - \frac{\pi}{m}, t + \frac{\pi}{m}\right) + \frac{\pi}{m}, \end{cases}$$

where

$$\phi = m(y + t), \quad \psi = n(y - t), \quad n = \sqrt{1 - m^2},$$

and  $m \in \mathbb{R}$  is a free parameter. For smooth modulated pulses,  $m < \sin(\pi/8) \approx 0.383$ .

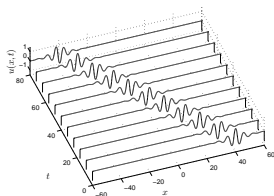


Figure: The pulse solution to the short-pulse equation with  $m = 0.25$

Nonlinear dispersive equations for short pulses have been justified in a similar context.

- D. Alterman, J. Rauch (2003) - geometric optics approach
- K. Barrailh, D. Lannes (2002); T. Colin, G. Gallice, K. Laurieux (2005) - nonlocal envelope equation with full dispersion
- M. Colin, D. Lannes (2009); D. Lannes (2011) - regularized nonlinear Schrödinger equation

For the short-pulse equation, only linearized equations were justified from Maxwell equations by using oscillatory integrals and Fourier analysis  
Y. Chung, C. Jones, T. Schäfer, C.E. Wayne (2005).

Let us consider the quasilinear Klein–Gordon–Maxwell equation,

$$u_{tt} - u_{xx} + u + (u^3)_{xx} = 0.$$

Using new variables,

$$u(t, x) = 2\epsilon U(\tau, \xi), \quad \tau = \epsilon t, \quad \xi = \frac{x - t}{2\epsilon},$$

the quasilinear equation can be written in the equivalent form,

$$U_{\tau\xi} = U + (U^3)_{\xi\xi} + \epsilon^2 U_{\tau\tau}.$$

The short-pulse equation appears by neglecting the last term  $\epsilon^2 U_{\tau\tau}$ ,

$$A_{\xi\tau} = A + (A^3)_{\xi\xi}.$$

**Main question:** Can this approximation be rigorously justified?



## Theorem

Fix  $s > \frac{7}{2}$  and  $T > 0$ . For sufficiently small  $\delta > 0$ , there exist  $\epsilon_0 > 0$  and  $C_0 > 0$  such that for all  $\epsilon \in (0, \epsilon_0)$ , the following holds:

Let  $A \in C([0, T], H^s(\mathbb{R}))$  be a local solution of the short-pulse equation such that

$$\sup_{\tau \in [0, T]} \|\partial_\tau^k A(\tau, \cdot)\|_{H^{s-k}} \leq \delta, \quad k = 0, 1, 2, 3,$$

and let  $U_0 \in H^3(\mathbb{R})$  and  $V_0 \in H^2(\mathbb{R})$  be such that

$$\|U_0 - A(0, \cdot)\|_{H^2} + \|V_0 - A_\tau(0, \cdot)\|_{H^1} \leq \epsilon.$$

There exists a unique solution

$$U \in C([0, T], H^3(\mathbb{R})) \cap C^1([0, T], H^2(\mathbb{R})) \cap C^2([0, T], H^1(\mathbb{R}))$$

of the quasilinear equation subject to the initial data  $U(0, \cdot) = U_0$ ,  $U_\tau(0, \cdot) = V_0$  satisfying

$$\sup_{\tau \in [0, T]} \|U(\tau, \cdot) - A(\tau, \cdot)\|_{H^2} \leq C_0 \epsilon.$$

- Local well-posedness of the short-pulse equation
- Remarks on the global well-posedness of the short-pulse equation
- Local well-posedness of the quasilinear equation
- Continuation criteria of the local solution of the quasilinear equation
- Energy estimates and the control of the approximation error.

## Assumptions of the theorem

We need to show that solutions of the short-pulse equation may satisfy

$$\sup_{\tau \in [0, T]} \|\partial_\tau^k A(\tau, \cdot)\|_{H^{s-k}} \leq \delta, \quad k = 0, 1, 2, 3.$$

**Proposition (Schäfer & Wayne, 2004; Stefanov *et al.*, 2010)**

*Fix  $s > \frac{3}{2}$ . For any  $A_0 \in H^s(\mathbb{R})$ , there exists a time  $\tau_0 > 0$  and a unique solution to the short-pulse equation such that*

$$A \in C([0, \tau_0], H^s(\mathbb{R})) \cap C^1((0, \tau_0], H^{s-1}(\mathbb{R}))$$

*and  $A(0, \cdot) = A_0$ . The solution depends continuously on  $A_0$ .*

To obtain estimates on  $\partial_\tau^k A$ , we note that

$$\begin{aligned} A_\tau &= \partial_\xi^{-1} A + (A^3)_\xi, \\ A_{\tau\tau} &= \partial_\xi^{-2} A + 3(A^2)_\xi \partial_\xi^{-1} A + 4A^3 + \frac{9}{5}(A^5)_{\xi\xi}, \\ A_{\tau\tau\tau} &= \partial_\xi^{-3} A + \partial_\xi^{-1} A^3 + 18A^2 \partial_\xi^{-1} A + 3(A^2)_\xi \partial_\xi^{-2} A + 6A_\xi (\partial_\xi^{-1} A)^2 \\ &\quad + \frac{27}{2}(A^4)_{\xi\xi} \partial_\xi^{-1} A + \frac{123}{5}(A^5)_\xi + \frac{27}{7}(A^7)_{\xi\xi\xi}, \end{aligned}$$

## Lemma

Let  $B_0 \in L^2(\mathbb{R})$  and consider the linear inhomogeneous equation,

$$\left. \begin{aligned} B_{\tau\xi} &= B + F, \\ B(0, \cdot) &= B_0. \end{aligned} \right\}$$

There exists a unique solution  $B \in C([0, \tau_0], L^2(\mathbb{R}))$  for some  $\tau_0 > 0$  if either (a)  $F = G_\xi$  with  $G \in C([0, \tau_0], L^2(\mathbb{R}))$  or (b)  $F \in C^1([0, \tau_0], L^2(\mathbb{R}))$ .

## Lemma

Let  $B_0 \in L^2(\mathbb{R})$  and consider the linear inhomogeneous equation,

$$\left. \begin{aligned} B_{\tau\xi} &= B + F, \\ B(0, \cdot) &= B_0. \end{aligned} \right\}$$

There exists a unique solution  $B \in C([0, \tau_0], L^2(\mathbb{R}))$  for some  $\tau_0 > 0$  if either (a)  $F = G_\xi$  with  $G \in C([0, \tau_0], L^2(\mathbb{R}))$  or (b)  $F \in C^1([0, \tau_0], L^2(\mathbb{R}))$ .

- If  $A_0 \in H^s(\mathbb{R}) \cap \dot{H}^{-1}(\mathbb{R})$ ,  $s > \frac{3}{2}$ , then

$$\partial_\xi^{-1} A \in C([0, \tau_0], H^{s+1}(\mathbb{R})), \quad A \in C^1([0, \tau_0], H^{s-1}(\mathbb{R})).$$

- If  $A_0 \in H^s(\mathbb{R}) \cap \dot{H}^{-2}(\mathbb{R})$ ,  $s > \frac{5}{2}$ , then

$$\partial_\xi^{-2} A \in C([0, \tau_0], H^{s+2}(\mathbb{R})), \quad A \in C^2([0, \tau_0], H^{s-2}(\mathbb{R})).$$

- If  $A_0 \in H^s(\mathbb{R}) \cap \dot{H}^{-2}(\mathbb{R})$ ,  $s > \frac{7}{2}$ , and  $\partial_\xi^{-3} A_0 + \partial_\xi^{-1} A_0^3 \in L^2(\mathbb{R})$ , then

$$A \in C^3([0, \tau_0], H^{s-3}(\mathbb{R}))$$

## Proposition (D.P., A. Sakovich, 2010)

If  $A_0 \in H^s(\mathbb{R})$ ,  $s \geq 2$  and

$$\|A'_0\|_{L^2}^2 + \|A''_0\|_{L^2}^2 < \frac{1}{6},$$

there exists  $C > 0$  and a unique solution  $A \in C(\mathbb{R}_+, H^s(\mathbb{R}))$  of the short-pulse equation with  $A(0, \cdot) = A_0$  such that  $\|A(\tau, \cdot)\|_{H^s} \leq C$ .

This result follows from conserved quantities [J.C. Brunelli (2005)]:

$$\dots, E_0 = \int_{\mathbb{R}} u^2 dx, \quad E_1 = \int_{\mathbb{R}} \frac{u_x^2}{1 + \sqrt{1 + u_x^2}} dx, \quad E_2 = \int_{\mathbb{R}} \frac{u_{xx}^2}{(1 + u_x^2)^{5/2}} dx, \dots$$

## Local well-posedness of the quasilinear equation

Starting with the quasilinear Klein–Gordon–Maxwell equation,

$$u_{tt} - u_{xx} + u + (u^3)_{xx} = 0.$$

we assume  $\|u\|_{L^\infty} < \frac{1}{\sqrt{3}}$  and introduce

$$u_1 = u_t, \quad u_2 = (1 - 3u^2)^{1/2} u_x, \quad u_3 = u.$$

The scalar equation is equivalent to the symmetric quasilinear system

$$\frac{\partial}{\partial t} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} + \begin{bmatrix} 0 & -(1 - 3u_3^2)^{1/2} & 0 \\ -(1 - 3u_3^2)^{1/2} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \frac{\partial}{\partial x} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \mathbf{f}(\mathbf{u}).$$

# Local well-posedness of the quasilinear equation

Starting with the quasilinear Klein–Gordon–Maxwell equation,

$$u_{tt} - u_{xx} + u + (u^3)_{xx} = 0.$$

we assume  $\|u\|_{L^\infty} < \frac{1}{\sqrt{3}}$  and introduce

$$u_1 = u_t, \quad u_2 = (1 - 3u^2)^{1/2} u_x, \quad u_3 = u.$$

The scalar equation is equivalent to the symmetric quasilinear system

$$\frac{\partial}{\partial t} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} + \begin{bmatrix} 0 & -(1 - 3u_3^2)^{1/2} & 0 \\ -(1 - 3u_3^2)^{1/2} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \frac{\partial}{\partial x} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \mathbf{f}(\mathbf{u}).$$

## Proposition (T. Kato, 1975)

*For any  $u_0 \in H^{s+1}(\mathbb{R})$  and  $v_0 \in H^s(\mathbb{R})$ ,  $s > \frac{3}{2}$  such that  $\|u_0\|_{L^\infty} < \frac{1}{\sqrt{3}}$ , there exists a time  $t_0 > 0$  and a unique solution of the quasilinear equation such that*

$$u \in C([0, t_0], H^{s+1}(\mathbb{R})) \cap C^1([0, t_0], H^s(\mathbb{R})) \cap C^2([0, t_0], H^{s-1}(\mathbb{R})),$$

*subject to  $u(0, \cdot) = u_0$  and  $u_t(0, \cdot) = v_0$ . Moreover, the local solution depends continuously on the initial data  $(u_0, v_0)$ .*



## Lemma

The local solution is continued on the time interval  $[0, t_0]$  for some  $t_0 > 0$  as long as

$$\sup_{t \in [0, t_0]} \|u(t, \cdot)\|_{L^\infty} < \frac{1}{\sqrt{3}} \quad \text{and} \quad \sup_{t \in [0, t_0]} (\|u_t(t, \cdot)\|_{L^\infty} + \|u_x(t, \cdot)\|_{L^\infty}) < \infty.$$

When  $s = 2 > \frac{3}{2}$ , the result follows from a priori estimates on the energy,

$$\begin{aligned} E_1(u) &= \int_{\mathbb{R}} (u^2 + u_t^2 + u_x^2(1 - 3u^2)) dx, \\ E_2(u) &= \int_{\mathbb{R}} (u_x^2 + u_{tx}^2 + u_{xx}^2(1 - 3u^2)) dx, \\ E_3(u) &= \int_{\mathbb{R}} (u_{xx}^2 + u_{txx}^2 + u_{xxx}^2(1 - 3u^2)) dx. \end{aligned}$$

For

$$E_1(u) = \int_{\mathbb{R}} (u^2 + u_t^2 + u_x^2(1 - 3u^2)) dx$$

we have from the quasilinear equation,

$$\frac{1}{2} \frac{dE_1(u)}{dt} = -3 \int_{\mathbb{R}} uu_t u_x^2 dx, \quad t \in [0, t_0],$$

Assume that  $M_{0,1,2} < \infty$ , where

$$M_0 = \sup_{t \in [0, t_0]} \|u(t, \cdot)\|_{L^\infty}, \quad M_1 = \sup_{t \in [0, t_0]} \|u_t(t, \cdot)\|_{L^\infty}, \quad M_2 = \sup_{t \in [0, t_0]} \|u_x(t, \cdot)\|_{L^\infty}.$$

Then,

$$\left| \frac{dE_1(u)}{dt} \right| \leq C(M_0)M_0M_1E_1(u) \quad \Rightarrow \quad E_1(u) \leq E_1(u_0)e^{C(M_0)M_0M_1t}, \quad t \in [0, t_0],$$

hence  $E_1(u)$  cannot blow up in a finite time  $t_0$ .

## Reformulation in new variables

Recall that in new variables,

$$u(t, x) = 2\epsilon U(\tau, \xi), \quad \tau = \epsilon t, \quad \xi = \frac{x - t}{2\epsilon},$$

the quasilinear equation can be written in the equivalent form,

$$U_{\tau\xi} = U + (U^3)_{\xi\xi} + \epsilon^2 U_{\tau\tau}.$$

### Lemma

*Fix  $C_0 > 0$  independently of  $\epsilon$ . For any  $U_0 \in H^{s+1}(\mathbb{R})$  and  $V_0 \in H^s(\mathbb{R})$ ,  $s > \frac{3}{2}$  such that  $\|U_0\|_{L^\infty} \leq C_0$ , there exists an  $\epsilon$ -independent time  $T_0 > 0$  and a unique solution of the rescaled quasilinear equation for any  $\epsilon \neq 0$  such that*

$$U(\tau, \cdot) \in C([0, \epsilon T_0], H^{s+1}(\mathbb{R})) \cap C^1([0, \epsilon T_0], H^s(\mathbb{R})) \cap C^2([0, \epsilon T_0], H^{s-1}(\mathbb{R})),$$

*subject to  $U(0, \cdot) = U_0$  and  $U_\tau(0, \cdot) = V_0$ . Moreover, the local solution is continued on the time interval  $[0, T]$  if*

$$\sup_{\tau \in [0, T]} \|U(\tau, \cdot)\|_{L^\infty} < C \quad \text{and} \quad \sup_{\tau \in [0, T]} (\|U_\tau(\tau, \cdot)\|_{L^\infty} + \|U_\xi(\tau, \cdot)\|_{L^\infty}) < \infty.$$

## Energy estimates for the error term

Setting  $U = A + \epsilon R$ , we obtain the quasilinear equation for the error term,

$$R_{\xi\tau} = R + \epsilon^2 R_{\tau\tau} + (3A^2 R + 3\epsilon A R^2 + \epsilon^2 R^3)_{\xi\xi} + \epsilon A_{\tau\tau}.$$

We shall control the energy for the error term,

$$E = \int_{\mathbb{R}} (R^2 + R_{\xi}^2 + R_{\xi\xi}^2 + 2\epsilon^2 R_{\tau}^2 + \epsilon^4 R_{\tau\tau}^2) dx.$$

By Sobolev embedding,  $R$  and  $R_{\xi}$  decay to zero at infinity as  $|\xi| \rightarrow \infty$  and

$$\|R\|_{L^{\infty}} + \|R_{\xi}\|_{L^{\infty}} \leq C E^{1/2}$$

From the quasilinear equation, we also have

$$\|R_{\xi\tau}\|_{L^2} \leq C \left( \delta\epsilon + E^{1/2} + \delta^2 E^{1/2} + \delta\epsilon E + \epsilon^2 E^{3/2} \right),$$

which yields the control of  $\|\epsilon R_{\tau}\|_{L^{\infty}} \leq C \left( E^{1/2} + \delta\epsilon^2 + \delta\epsilon^2 E + \epsilon^3 E^{3/2} \right)$ .

## Summary of the prerequisites:

(1) We have seen that the short-pulse equation has local solutions  $A \in C([0, T], H^s(\mathbb{R}))$  for fixed  $T > 0$ ,  $s > \frac{7}{2}$  and sufficiently small  $\delta > 0$ :

$$\sup_{\tau \in [0, T]} \|\partial_\tau^k A(\tau, \cdot)\|_{H^{s-k}} \leq \delta, \quad k = 0, 1, 2, 3.$$

## Summary of the prerequisites:

(1) We have seen that the short-pulse equation has local solutions  $A \in C([0, T], H^s(\mathbb{R}))$  for fixed  $T > 0$ ,  $s > \frac{7}{2}$  and sufficiently small  $\delta > 0$ :

$$\sup_{\tau \in [0, T]} \|\partial_\tau^k A(\tau, \cdot)\|_{H^{s-k}} \leq \delta, \quad k = 0, 1, 2, 3.$$

(2) If the initial data satisfy

$$\|U(0, \cdot) - A(0, \cdot)\|_{H^2} + \|V(0, \cdot) - A_\tau(0, \cdot)\|_{H^1} \leq \epsilon,$$

then

$$\|R(0, \cdot)\|_{H^2} + \|R_\tau(0, \cdot)\|_{H^1} \leq 1,$$

or  $E < \infty$ .

## Summary of the prerequisites:

(1) We have seen that the short-pulse equation has local solutions  $A \in C([0, T], H^s(\mathbb{R}))$  for fixed  $T > 0$ ,  $s > \frac{7}{2}$  and sufficiently small  $\delta > 0$ :

$$\sup_{\tau \in [0, T]} \|\partial_\tau^k A(\tau, \cdot)\|_{H^{s-k}} \leq \delta, \quad k = 0, 1, 2, 3.$$

(2) If the initial data satisfy

$$\|U(0, \cdot) - A(0, \cdot)\|_{H^2} + \|V(0, \cdot) - A_\tau(0, \cdot)\|_{H^1} \leq \epsilon,$$

then

$$\|R(0, \cdot)\|_{H^2} + \|R_\tau(0, \cdot)\|_{H^1} \leq 1,$$

or  $E < \infty$ .

(3) If  $U(0, \cdot) \in H^3(\mathbb{R})$ , and  $V(0, \cdot) \in H^2(\mathbb{R})$ , then there exists a local solution of the quasilinear equation for the error term,

$$R \in C([0, \epsilon T], H^3(\mathbb{R})) \cap C^1([0, \epsilon T], H^2(\mathbb{R})) \cap C^2([0, \epsilon T], H^1(\mathbb{R}))$$

The existence interval is extended as long as  $R$  is controlled in the energy space  $E(\tau) < \infty$  for  $\tau \in [0, T]$ .

(1) We have the energy estimates:

$$\frac{dE}{d\tau} = J, \quad |J| \leq C \left( \delta E^{1/2} + \delta^2 E + \delta E^{3/2} + \epsilon E^2 \right),$$

for some  $(\epsilon, \delta)$ -independent constant  $C > 0$ , as long as the solution remains in the function space

$$R \in C([0, T], H^3(\mathbb{R})) \cap C^1([0, T], H^2(\mathbb{R})) \cap C^2([0, T], H^1(\mathbb{R})).$$



(1) We have the energy estimates:

$$\frac{dE}{d\tau} = J, \quad |J| \leq C \left( \delta E^{1/2} + \delta^2 E + \delta E^{3/2} + \epsilon E^2 \right),$$

for some  $(\epsilon, \delta)$ -independent constant  $C > 0$ , as long as the solution remains in the function space

$$R \in C([0, T], H^3(\mathbb{R})) \cap C^1([0, T], H^2(\mathbb{R})) \cap C^2([0, T], H^1(\mathbb{R})).$$

(2) By Gronwall's inequality, there exist  $C_0, C_1 > 0$  such that

$$E(\tau) \leq C_0(E(0) + \delta T)e^{C_1\delta T}, \quad \tau \in [0, T].$$

This bound allows us to continue the solution from  $[0, \epsilon T]$  to  $[0, T]$ .

(1) We have the energy estimates:

$$\frac{dE}{d\tau} = J, \quad |J| \leq C \left( \delta E^{1/2} + \delta^2 E + \delta E^{3/2} + \epsilon E^2 \right),$$

for some  $(\epsilon, \delta)$ -independent constant  $C > 0$ , as long as the solution remains in the function space

$$R \in C([0, T], H^3(\mathbb{R})) \cap C^1([0, T], H^2(\mathbb{R})) \cap C^2([0, T], H^1(\mathbb{R})).$$

(2) By Gronwall's inequality, there exist  $C_0, C_1 > 0$  such that

$$E(\tau) \leq C_0(E(0) + \delta T)e^{C_1\delta T}, \quad \tau \in [0, T].$$

This bound allows us to continue the solution from  $[0, \epsilon T]$  to  $[0, T]$ .

(3) As a result, we have obtained a local solution,

$$U \in C([0, T], H^3(\mathbb{R})) \cap C^1([0, T], H^2(\mathbb{R})) \cap C^2([0, T], H^1(\mathbb{R})),$$

satisfying

$$\sup_{\tau \in [0, T]} \|U(\tau, \cdot) - A(\tau, \cdot)\|_{H^2} \leq C_0\epsilon.$$

Solutions of the quasilinear Klein–Gordon–Maxwell equation,

$$u_{tt} - u_{xx} + u + (u^3)_{xx} = 0,$$

which are initially closer to small solutions of the short-pulse equation,

$$A_{\xi\tau} = A + (A^3)_{\xi\xi},$$

remain close to these solutions for long but finite time intervals.

Solutions of the quasilinear Klein–Gordon–Maxwell equation,

$$u_{tt} - u_{xx} + u + (u^3)_{xx} = 0,$$

which are initially closer to small solutions of the short-pulse equation,

$$A_{\xi\tau} = A + (A^3)_{\xi\xi},$$

remain close to these solutions for long but finite time intervals.

Initial proximity

$$\left\| u(0, \cdot) - 2\epsilon A \left( 0, \frac{\cdot}{2\epsilon} \right) \right\|_{H^2} \leq C\epsilon^{1/2}, \quad \left\| u_t(0, \cdot) + A_\xi \left( 0, \frac{\cdot}{2\epsilon} \right) \right\|_{H^1} \leq C\epsilon^{1/2},$$

implies

$$\sup_{t \in [0, T/\epsilon]} \left\| u(t, \cdot) - 2\epsilon A \left( \epsilon t, \frac{\cdot - t}{2\epsilon} \right) \right\|_{H^2} \leq C_0 \epsilon^{1/2},$$

where the leading-order term is

$$\left\| \epsilon A_0 \left( \frac{\cdot}{2\epsilon} \right) \right\|_{H^2} = \mathcal{O}(\epsilon^{-1/2}), \quad \left\| A'_0 \left( \frac{\cdot}{2\epsilon} \right) \right\|_{H^1} = \mathcal{O}(\epsilon^{-1/2}).$$

# Criteria of well-posedness and wave breaking

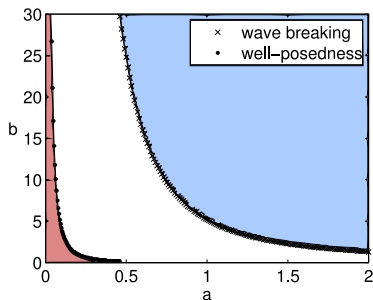
Consider the short-pulse equation

$$u_{xt} = u + \frac{1}{6} (u^3)_{xx},$$

with Gaussian initial data

$$u_0(x) = a(1 - 2bx^2)e^{-bx^2}, \quad x \in \mathbb{R},$$

where  $(a, b)$  are arbitrary and  $\int_{\mathbb{R}} u_0(x) dx = 0$  is satisfied.



**Figure:** Global solutions exist in the red region and wave breaking occurs in the blue region [D.P., A. Sakovich, 2010].

Using the pseudospectral method, we solve

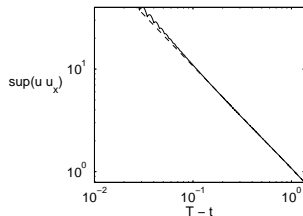
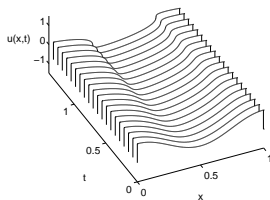
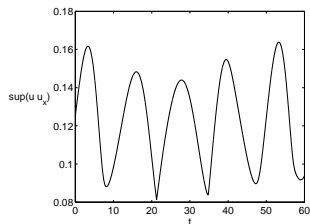
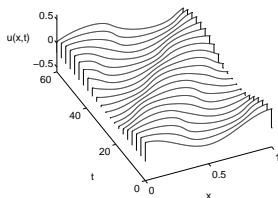
$$\frac{\partial}{\partial t} \hat{u}_k = -\frac{i}{k} \hat{u}_k + \frac{ik}{6} \mathcal{F} \left[ (\mathcal{F}^{-1} \hat{u})^3 \right]_k, \quad k \neq 0, \quad t > 0.$$

Consider the 1-periodic initial data

$$u_0(x) = a \cos(2\pi x)$$

- Criterion for wave breaking:  $a > 1.053$ .
- Criterion for global solutions:  $a < 0.0354$ .

# Evolution of the cosine initial data



**Figure:** Solution surface  $u(x,t)$  (left) and the supremum norm  $W(t)$  (right) for  $a = 0.2$  (top) and  $a = 0.5$  (bottom).

- Does the approximation error grow for wave breaking solutions?
- Can the justification analysis be extended to models with dispersive regularizations of the short-pulse equation, when no wave breaking may occur?
- Does the justification analysis hold for short-wave (quadratic nonlinearity) equation?